Qualitative structure of perturbations propagation process of the Fisher–Kolmogorov equation with a deviation of spatial variable

Sergey Aleshin, Sergey Glyzin

P.G. Demidov Yaroslavl State University

November 17-19, 2015

S.V. Aleshin, S.D. Glyzin

In 1937 Kolmogorov, Petrovskii and Piskunov [1] proposed the logistic equation with diffusion for simulate the propagation of genetically wave

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + u[1-u],\tag{1}$$

In the same year Fisher [2] published the article devoted to the analysis of a similar equation.

- Kolmogorov A., Petrovsky I., Piscounov N. Étude de l'équation de la diffusion avec croissance de la quantité de matière et son application à un problème biologique // Moscou Univ. Bull. Math., 1 (1937). P. 1–25.
- 2 Fisher R.A. The Wave of Advance of Advantageous Genes // Annals of Eugenics. 1937. V. 7. P. 355–369.

S.V. Aleshin, S.D. Glyzin

Qualitative structure of perturbations propagation process of the Fisher-Kolmogorov equation with a deviation of spatial variable

Introduction

Logistic equation generalization for simulation of population density distribution with dependencies of spatial and time deviations was considered in [1-3].

$$\frac{\partial u(t,x)}{\partial t} = \Delta u(t,x) + u(t,x)[1 + \alpha u(t,x) - (1 + \alpha(g * u)(t,x)]$$
(2)

and convolution has following form

$$(g * u)(t, x) = \int_{-\infty}^{t} \int_{\Omega} g(t - \tau, x - y)u(\tau, y)dyd\tau,$$
(3)

- Gourley S. A., So J. W.-H., Wu J. H. Nonlocality of Reaction-Diffusion Equations Induced by Delay: Biological Modeling and Nonlinear Dynamics // Journal of Mathematical Sciences. 2004. Vol. 124, Issue 4. PP 5119–5153.
- 2 Britton N. F. Reaction-diffusion equations and their applications to biology / New York: Academic Press, 1986.
- 3 Britton N. F. Spatial structures and periodic travelling waves in an integro-differential reaction-diffusion population model // SIAM J. Appl. Math. 1990. V. 50. P. 1663–1688.

S.V. Aleshin, S.D. Glyzin

Logistic equation with a deviation of spatial variable

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} + u[1 - u(t, x - h)].$$
(4)

$$u(t,x) = w(2t \pm x) \quad s = 2t \pm x$$

$$w'' - 2w' + w[1 - w(s - h)] = 0,$$
(5)

$$P(\lambda) \equiv \lambda^2 - 2\lambda - \exp(-h\lambda).$$
 (6)

S.V. Aleshin, S.D. Glyzin

Logistic equation with a deviation of spatial variable

$$\lambda^{2} - 2\lambda - \exp(-h\lambda) = 0,$$

$$2\lambda - 2 - h \exp(-h\lambda) = 0.$$

$$\lambda \approx -1.23141 \quad h = h_{1}^{*} \approx 1.12154$$
(7)

Lemma (1)

Quasipolynomial $P(\lambda)$ has one positive and two negative real roots at $0 < h < h_1^*$ and only one positive real root at $h > h_1^*$.

Lemma (2)

All roots of quasipolinom $P(\lambda)$ lie in the left half-plane for $0 < h < h_2^*$, except for one real positive root. Here $h_2^* = \frac{\arccos{(-\sqrt{5}+2)}}{\sqrt{\sqrt{5}-2}} \approx 3.72346$, The pair $\lambda = \pm i\omega_0$ of pure imaginary roots goes to the imaginary axis at $h = h_2^*$ and $\omega_0 = \sqrt{\sqrt{5}-2} \approx 0.48587$.

S.V. Aleshin, S.D. Glyzin

$$h = h_2^* + \mu \quad 0 < \mu \ll 1$$

$$w(s,\mu) = 1 + \sqrt{\mu} (z(\tau) \exp(i\omega_0 s) + \bar{z}(\tau) \exp(-i\omega_0 s)) + + \mu w_1(s,\tau) + \mu^{3/2} w_2(s,\tau) + \dots, \quad \tau = \mu s, w_j(s,\tau) (j=1,2)$$
(8)

$$\frac{dz}{d\tau} = \varphi_0 z + \varphi_1 |z|^2 z, \tag{9}$$

$$\begin{aligned} &\mathsf{at} \; \varphi_0 = \frac{2\omega_0^2(-1+i\omega_0)}{P'(i\omega_0)}, \\ &\varphi_1 = \frac{1}{P'(i\omega_0)} \bigg(2\omega_0^2(1-\omega_0^2-2i\omega_0) + \beta \Big((\omega_0^2+2i\omega_0)^2 - \frac{1}{\omega_0^2+2i\omega_0} \Big) \Big), \\ &\beta = \frac{\omega_0^2+2i\omega_0}{4\omega_0^2+4i\omega_0 + (\omega_0^2+2i\omega_0)^2}. \\ &\varphi_0 \approx 0.136807 - 0.20660i \quad \varphi_1 \approx -0.04429 - 0.03664i \end{aligned}$$

S.V. Aleshin, S.D. Glyzin

Lemma (3)

Let $h = h_2^* + \mu$ and $0 < \mu \ll 1$ then there exists $\mu_0 > 0$ such that for all $0 < \mu < \mu_0$ equation (5) has dichotomous cycle which one-dimensional unstable manifold and following asymptotic

 $\sqrt{-\operatorname{Re}\left(\varphi_{0}\right)/\operatorname{Re}\left(\varphi_{1}\right)}\exp\left(i\varepsilon s\left(\operatorname{Im}\left(\varphi_{0}\right)\operatorname{Re}\left(\varphi_{1}\right)-\operatorname{Re}\left(\varphi_{0}\right)\operatorname{Im}\left(\varphi_{1}\right)\right)/\operatorname{Re}\left(\varphi_{0}\right)+i\gamma\right)$

and γ — is an arbitrary constant, which determines the phase shift along the cycle.

Logistic equation with a deviation of spatial variable

$$u(t,x) = u(t,x+T), \quad T > 0$$
 (10)

$$\frac{\partial v}{\partial t} = \frac{\partial^2 v}{\partial x^2} - v(t, x - h), \quad v(t, x) = v(t, x + T).$$
(11)

$$v(t,x) = \exp \lambda \exp i\omega x$$

$$\lambda = -\omega^2 - \exp i\omega h.$$
(12)

$$h^* = 2.791544, \quad \omega^* = 0.88077.$$
 (13)

S.V. Aleshin, S.D. Glyzin

$$T = 2\pi/\omega^* \quad h = h^* + \varepsilon$$

$$u(t, x, \varepsilon) = 1 + \sqrt{\varepsilon} u_0(t, \tau, x) + \varepsilon u_1(t, \tau, x) + \varepsilon^{3/2} u_2(t, \tau, x) + \dots,$$
 (14) and $\tau = \varepsilon t$,

$$u_0(t,\tau,x) = z(\tau) \exp\left(i(\omega_0 t + \omega^* x)\right) + \bar{z}(\tau) \exp\left(-i(\omega_0 t + \omega^* x)\right), \quad \omega_0 = \sin\omega^* h^*.$$

$$\frac{dz}{d\tau} = \varphi_0 z + \varphi_1 |z|^2 z, \tag{15}$$

$$\begin{aligned} \varphi_0 &= i\omega^* \exp(-i\omega^* h^*), \\ \varphi_1 &= 2\cos\omega^* h^* (1 + \exp(-i\omega^* h^*)) - (\exp(-2i\omega^* h^*) + \exp(i\omega^* h^*)) w_2. \\ \varphi_0 &\approx 0.5558 - 0.6833i, \quad \varphi_1 \approx -0.1701 + 0.59i. \end{aligned}$$

S.V. Aleshin, S.D. Glyzin

Lemma (4)

Let $h = h^* + \varepsilon$ then there exists $\varepsilon_0 > 0$ such that for all $0 < \varepsilon < \varepsilon_0$ boundary value problem (4), (10) has orbitally asymptotically stable cycle with following asymptotic

 $\sqrt{-\operatorname{Re}\left(\varphi_{0}\right)/\operatorname{Re}\left(\varphi_{1}\right)}\exp\left(i\varepsilon t\left(\operatorname{Im}\left(\varphi_{0}\right)\operatorname{Re}\left(\varphi_{1}\right)-\operatorname{Re}\left(\varphi_{0}\right)\operatorname{Im}\left(\varphi_{1}\right)\right)/\operatorname{Re}\left(\varphi_{0}\right)+i\gamma\right)$

and γ — is an arbitrary constant, which determines the phase shift along the cycle.

$$\dot{u}_{j} = \frac{u_{j+1} - 2u_{j} + u_{j-1}}{(\Delta x)^{2}} + [1 - u_{j-k}]u_{j},$$
(16)

$$j = 0, \dots, N - 1, \ k = \lfloor h/\Delta x \rfloor$$

$$N = 1.8 \cdot 10^{5} \quad N = 1.8 \cdot 10^{6}$$

$$u_{j}(0) = \begin{cases} 0.1, \ \text{if } j \in [89950, 90050], \\ 0, \ \text{otherwise.} \end{cases}$$
(17)

S.V. Aleshin, S.D. Glyzin



Wave propagation in logistic equation with spatial variable deviation h=1.2 and cross-section t=425

S.V. Aleshin, S.D. Glyzin



Wave propagation in logistic equation with spatial variable deviation h=2.7 and cross-section t=425

S.V. Aleshin, S.D. Glyzin

h = 2.81



Wave propagation in logistic equation with spatial variable deviation h=2.81 and cross-section $t=4500\,$

S.V. Aleshin, S.D. Glyzin

movie

S.V. Aleshin, S.D. Glyzin



Wave propagation in logistic equation with spatial variable deviation $h=3 \mbox{ and } cross-section \ t=425$

S.V. Aleshin, S.D. Glyzin

Thank you for attention!

S.V. Aleshin, S.D. Glyzin